

ISBN 82-553-0586-6

No 6

September 23

1985

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by

Jan Arthur Christophersen

PREPRINT SERIES - Matematisk institutt, Univ. i Oslo

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It is proved in [D] that the topological type of an isolated curve singularity on a toric surface depends only on its Newton filtration. In this note we give as a corollary of Kouchnirenko's theorem I in [K] a similar formula for the Milnor number of singularities defined by one analytic function on a normal affine two dimensional toric variety. I would like to thank James Damon for his helpful remarks.

1. The toric surface as quotient singularity

Any complex normal affine toric surface is isomorphic to one of the type $X = \text{Spec}(\mathbb{C}[\Lambda])$ where $\Lambda = \sigma \cap \mathbb{Z}^2$, σ is a rational polyhedral cone in \mathbb{R}_+^2 and $\mathbb{C}[\Lambda]$ is the semigroup ring of Λ over \mathbb{C} .

(See [O])

Let σ be generated by $M_1 = (m_1, n_1)$ and $M_2 = (m_2, n_2)$, i.e. $M_1, M_2 \in \mathbb{Z}_+^2$, $\gcd(m_i, n_i) = 1$, $\det(M_1, M_2) > 0$ and $\sigma = \{\alpha_1 M_1 + \alpha_2 M_2 \mid \alpha_i \in \mathbb{R}_+\}$. It is well known that $X = \mathbb{C}^2/G$ where G is a finite cyclic group acting freely outside the origin. One way of seeing this is as follows: Let $G = \{\alpha_1 M_1 + \alpha_2 M_2 \mid \alpha_i \in \mathbb{R}, 0 \leq \alpha_i < 1\} \cap \mathbb{Z}^2$. Then G is a cyclic group of order $d = \det(M_1, M_2)$; the group addition is vector addition modulo $\langle M_1, M_2 \rangle$.

Define two linear maps $v_1, v_2: \mathbb{Z}^2 \rightarrow \mathbb{Z}$ by $v_1(x) = \det(x, M_2)$, $v_2(x) = \det(M_1, x)$. These restrict to $v_i: G \rightarrow \{0, 1, \dots, d-1\}$ and induce group isomorphisms $\bar{v}_i: G \xrightarrow{\sim} \mathbb{Z}_d$, $\bar{v}_i(a) = v_i(a) \pmod{d}$. We have an action of G on $\mathbb{C}[x, y]$; for $a \in G$

$$a.x = e^{\frac{-2\pi i v_2(a)}{d}} x$$

$$a.y = e^{\frac{2\pi i v_1(a)}{d}} y$$

Let $T: \mathbb{Z}^2 \rightarrow \mathbb{Z}^2$ be the linear transformation $T(m,n) = (v_1(m,n), v_2(m,n))$. It's matrix is $\begin{pmatrix} n_2 & -m_2 \\ -n_1 & m_1 \end{pmatrix}$. Of course $\mathbb{C}[\Lambda] = \mathbb{C}[T(\Lambda)] \subseteq \mathbb{C}[x,y]$ and one checks that $\mathbb{C}[T(\Lambda)] = \mathbb{C}[x,y]^G$.

On the other hand, given a cyclic group $G \subseteq GL_2(\mathbb{C})$ and an action on \mathbb{C}^2 one can easily construct a cone $\sigma \subseteq \mathbb{R}_+^2$ such that $\text{Spec } \mathbb{C}[\sigma \cap \mathbb{Z}^2] = \mathbb{C}^2/G$.

2. The Milnor number of a function on X

Assume f is an analytic function $f: X \rightarrow \mathbb{C}$ with an isolated critical point at 0. We know that f has a Milnor fibration $[L]$, i.e. a \mathbb{C}^∞ fibration

$$B_\varepsilon \cap X \cap f^{-1}(D_\eta^*) \rightarrow D_\eta^*$$

induced by f , where B_ε is a closed regular ball in \mathbb{C}^e with radius $\varepsilon > 0$ and D_η^* is a punctured disc of radius η in \mathbb{C} . (Here e denotes the embedding dimension of X .) If F is the typical Milnor fiber we can define $\mu(f) = \text{rk } H_1(F)$ to be the Milnor number of the curve $f^{-1}(0)$ at 0.

We are now in the following situation:

$$\begin{array}{ccc} \bar{F} \subseteq \mathbb{C}^2, 0 & \searrow \bar{f} & \\ \pi \downarrow & & \\ F \subseteq X, 0 & \xrightarrow{f} & \mathbb{C}, 0 \end{array}$$

π is the natural map $\pi: \mathbb{C}^2 \rightarrow \mathbb{C}^2/G$.

Here $\bar{f} = f \circ \pi$ and \bar{F} is the Milnor fiber of \bar{f} at the origin.

The embedding $\phi: X \rightarrow \mathbb{C}^e$ is given by monomials in x and y generating $\mathbb{C}[x, y]^G$. Call these generators for ϕ_1, \dots, ϕ_e and put $w_i = \deg \phi_i$. Then $\phi = \phi \circ \pi: \mathbb{C}^2 \rightarrow \mathbb{C}^e$ is the map $\phi(x, y) = (\phi_1(x, y), \dots, \phi_e(x, y))$. If N is any positive number let

$$B'_{\varepsilon, N} = \{z \in \mathbb{C}^e: \sum_{i=1}^e |z_i|^{2b_i} < \varepsilon, b_i \cdot w_i = N\}.$$

The Milnor fiber constructed from regular balls in \mathbb{C}^e is diffeomorphic to the Milnor fiber using "weighted" balls of the form $B'_{\varepsilon, N}$ for suitable choice of ε .

Notice that:

1) The unit sphere in \mathbb{C}^2 is compact so,

$$\max \{|\phi_1(x, y)|^2, \dots, |\phi_e(x, y)|^2: |(x, y)| = 1\} \text{ exists.}$$

$$\begin{aligned} 2) \quad \sum_{i=1}^e |\phi_i(x, y)|^{2b_i} &= \sum_{i=1}^e |(x, y)|^{2b_i w_i} \cdot \left| \phi_i\left(\frac{(x, y)}{|(x, y)|}\right) \right|^{2b_i} \\ &= |(x, y)|^{2N} \sum_{i=1}^e \left| \phi_i\left(\frac{(x, y)}{|(x, y)|}\right) \right|^{2b_i} \end{aligned}$$

It follows that for appropriate ε and N , ϕ maps a regular ball of \mathbb{C}^2 onto $X \cap B'_{\varepsilon}$. This means we can assume that $F = \bar{F}/G$;

hence $\chi(\bar{F}) = (\text{ord } G) \cdot \chi(F)$, where χ is the Euler characteristic.

But since we are dealing with curves,

$\chi(\bar{F}) = 1 - \mu(\bar{f})$ and $\chi(F) = 1 - \mu(f)$, so

$$\mu(f) = 1 + \frac{\mu(\bar{f}) - 1}{d}.$$

Recall Kouchnirenko's formula for the Milnor number of a plane curve at the origin. A power series $g \in \mathbb{C}[[x_1, x_2]]$ is "commodore" if the monomials x_1^m and x_2^n , $m, n \geq 1$, appear in g with non zero coefficients. If m and n are the minimal such numbers, then the

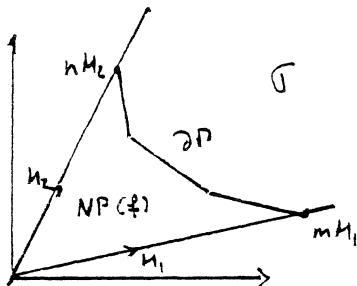
Newton number $v(g)$ is defined as $2A-m-n+1$ where A is the area bounded by the Newton polygon $NP(g)$ of g . If g is not "commode" then $v(g)$ is defined by $v(g) = \sup_{m \in \mathbb{N}} v(g + \sum x_i^m)$ where the sum is now taken over the variables, a power of which does not appear alone in g . The theorem then states that if g has an isolated critical point at 0 and if g is nondegenerate (see [K], page 7, for the definition) then $\mu(g) = v(g)$.

Identifying an analytic $f: X \rightarrow \mathbb{C}$ with a power series in the monomials of $\mathbb{C}[\Lambda]$, we can define its Newton polygon as follows. If

$$f = \sum_{(i,j) \in \Lambda} c_{ij} x^i y^j, \text{ let } \Gamma \text{ be the convex hull in } \sigma \text{ of } U\{(i,j) + \sigma\}$$

where $(i,j) \in \{(i,j) | c_{ij} \neq 0\}$. Call f commode if the monomials

$(x^{m_1} y^{n_1})^m$ and $(x^{m_2} y^{n_2})^n$ appear with non zero coefficients. If f is commode then define the Newton polygon $NP(f)$ to be the polygon given by the boundary of Γ and the rays through M_1 and M_2 .



Define the Newton number as

$v(f) = 2S - m - n + 1$ where S is the area bounded by $NP(f)$ and m and n are chosen minimally as above. If f is not commode, then define $v(f)$ as in the case of plane curves above.

To make the definitions simple we will say that f is non-degenerate if $\bar{f} = f \circ \pi$ is nondegenerate.

Theorem Let $f: X \rightarrow \mathbb{C}$ be an analytic function with an isolated critical point at the origin. If f is nondegenerate, then $\mu(f) = v(f)$.

Proof. Each monomial in \bar{f} is just the image of the corresponding monomial in f by the mapping $\mathbb{C}[\Lambda] \xrightarrow{\sim} \mathbb{C}[T(\Lambda)] \rightarrow \mathbb{C}[x, y]$. So $NP(\bar{f})$ is just the image of $NP(f)$ by

$$T = \begin{pmatrix} n_2 & -m_2 \\ -n_1 & m_1 \end{pmatrix} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

If f is commode, $f = (x_1^{m_1} y_1^{n_1})^m + (x_2^{m_2} y_2^{n_2})^n + \dots$, then the area bounded by $NP(\bar{f})$ is $(\det T) \cdot S = d \cdot S$. Since $T(mM_1) = (md, 0)$, $T(nM_2) = (0, nd)$,

$$\mu(\bar{f}) = v(\bar{f}) = 2Sd - md - nd + 1$$

Consequently

$$\mu(f) = 1 + \frac{\mu(\bar{f}) - 1}{d} = 2S - m - n + 1 = v(f)$$

The same argument obviously holds in the non-commode case. \square

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University of Oslo
Inst. of Mathematics
P.B. 1053, Blindern
0316 Oslo 3
NORWAY